

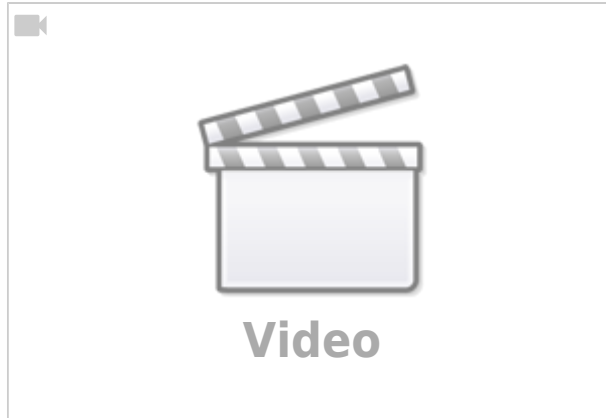
# [Robótica] Canal de Juan Carlos Martín Castillo

## RAPID avanzado



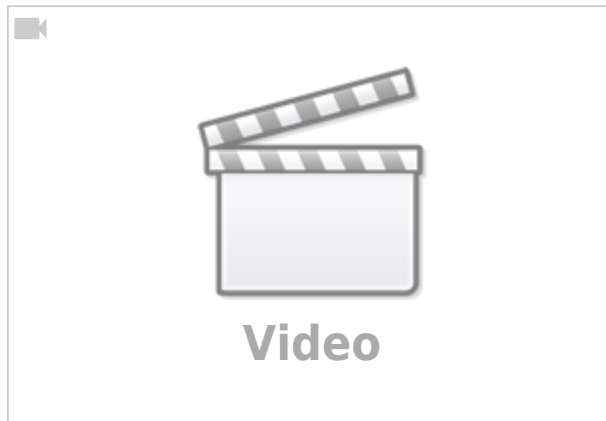
1

01 - Tipos de datos y procedimiento con argumentos (21m 48s)



2

02 - AliasIO para controlar salidas digitales (7m 47s)



3

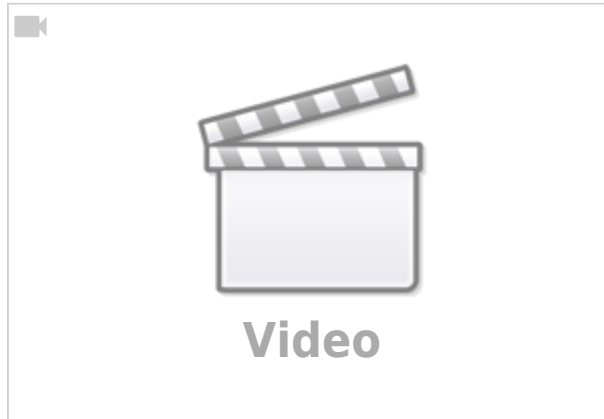
03 - Posicionamiento basado en variables (uso del pos.trans y Cpos) (34m 48s)





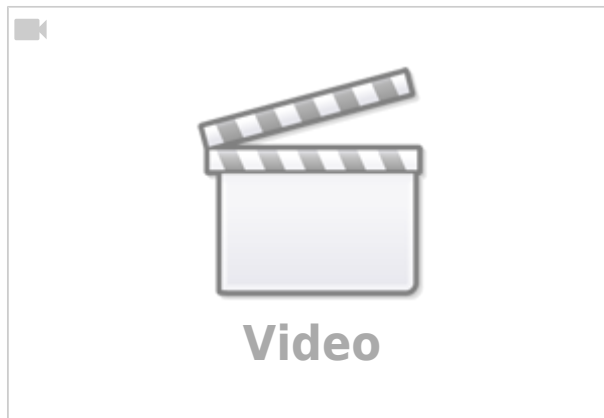
4

[04 - Array de posiciones tipo rotarget \(11m 11s\)](#)



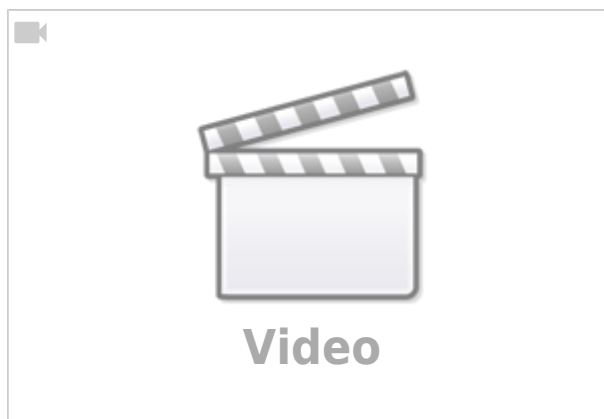
5

[05 - Paletizado con Offset y bucles FOR \(22m 6s\)](#)

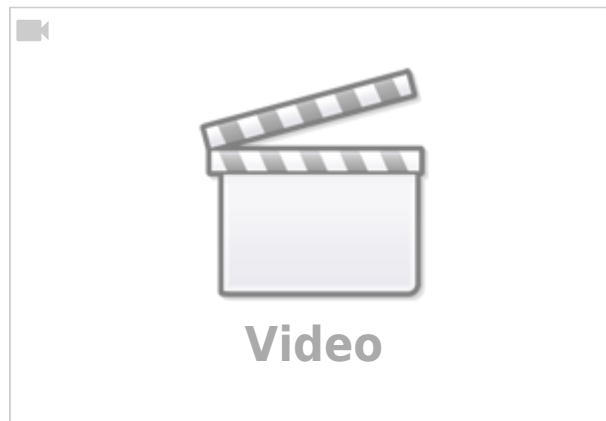


6

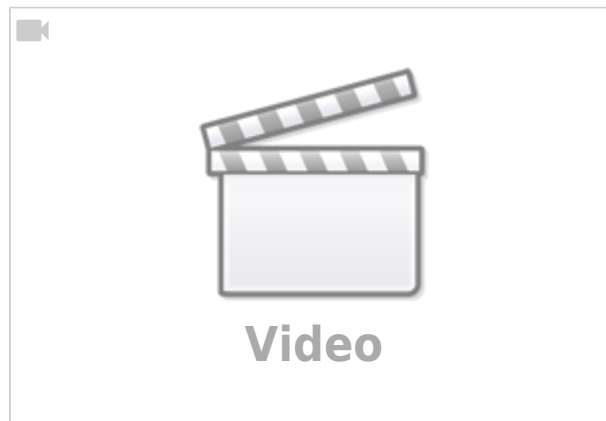
[06 - Trayectoria rectangular dinámica \(18m 38s\)](#)



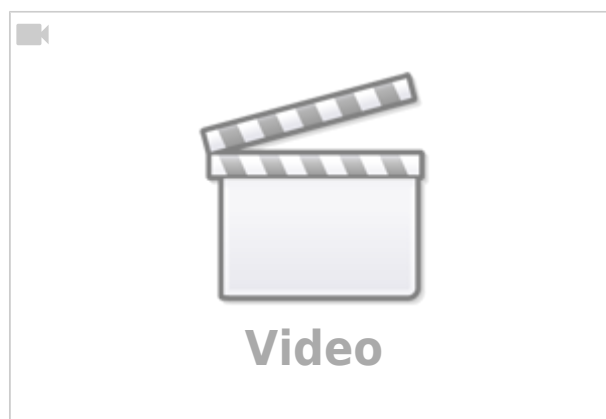
7

[07 - Trayectoria triangular dinamica \(11m 22s\)](#)

8

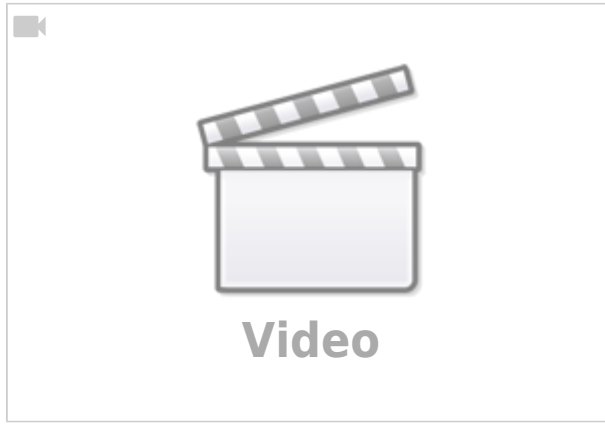
[08 - Trayectoria circular dinamica \(14m 5s\)](#)

9

[09 - Posicionamiento relativo Offs vs RelTool \(14m 25s\)](#)

10

[10 - Trayectoria circular dinamica con Offs y RelTool \(7m 24s\)](#)



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