

# [Robótica] RobotStudio: Mecanismos



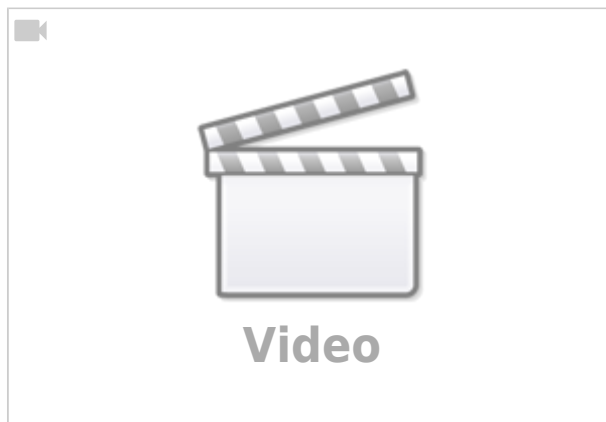
1

[DESPLAZAMIENTO DE ROBOT CON TRACK \(14m 17s\)](#)



2

[ROBOT STUDIO \(E\\_S digitales y creación o modificación de mecanismos\)\(31m 12s\)](#)



3

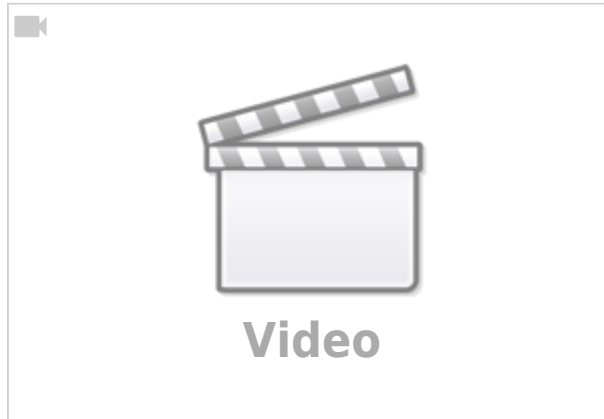
[RobotStudio Practica 14D Utilizacion de componentes inteligentes vacíos \(8m 52s\)](#)





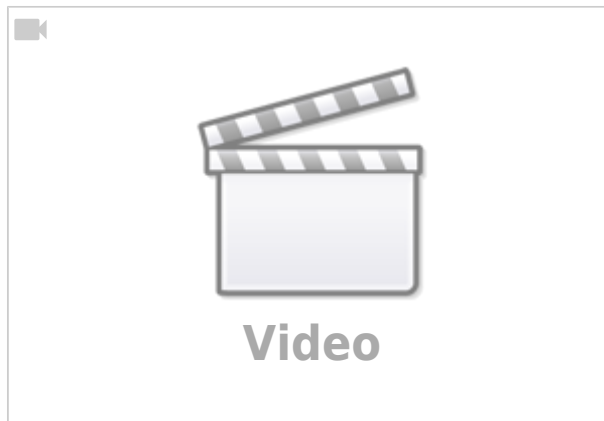
4

[RobotStudio\\_smart gripper 1 \(10m\)](#)



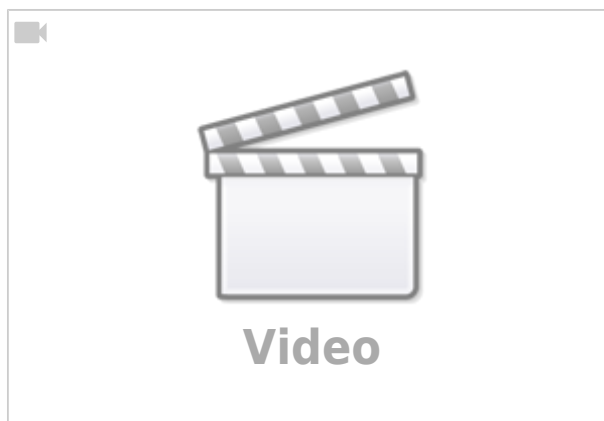
5

[RobotStudio\\_smart gripper 2 \(31m 30s\)](#)

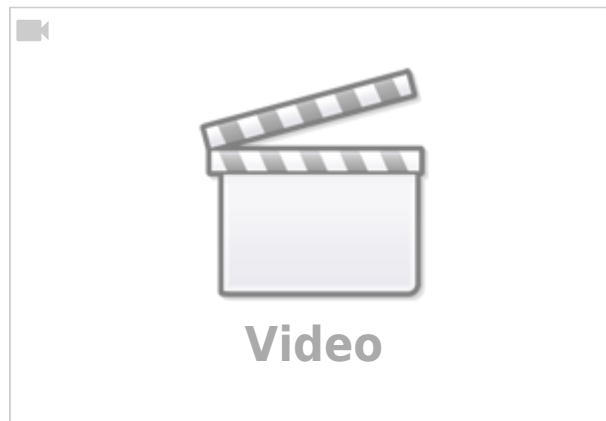


6

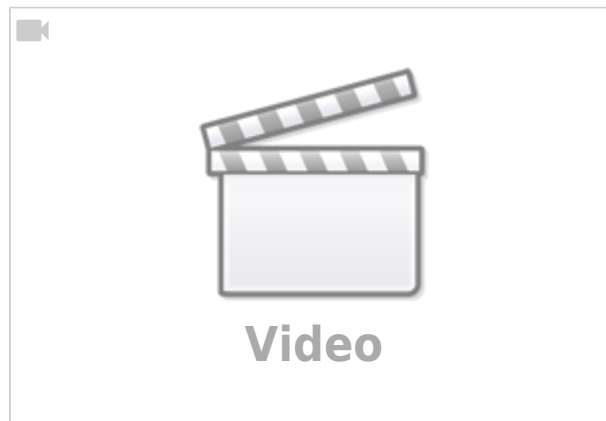
[RobotStudio\\_smart gripper 3 \(2m 5s\)](#)



7

[RobotStudio\\_smart pinza \(23m 10s\)](#)

8

[Tutorial del Proyecto Final de curso ROBOT-STUDIO \(5h 47m 11s\)](#)

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